

## **Applications of Al in Vehicles**



#### Advanced Driver Assistance Systems (ADAS)

- Object detection and recognition
- Driver assistance
- Driver monitoring

#### Autonomous Driving

- Perception (sensor fusion)
- Path planning
- Vehicle command and control
- Safety monitoring

#### Predictive Maintenance

- Realtime vehicle data analysis
- Recognize failure relevant deviations
- Optimize service content and intervals

#### Vehicle User Interface

- Speech recognition and response
- Personalization
- Driver emotion monitoring & intervention

#### Cybersecurity

- Detect anomalies in vehicle network traffic
- Realtime cyberattack identification
- Realtime intrusion defense

#### Energy Management

- Range prediction
- Battery usage optimization



## Challenges of Al in Vehicles



- Safety and Reliability
  - Unexpected behavior
  - Overfitting
  - Hallucinations
  - Black-box nature
- Data Privacy
  - Risk of data leaks or misuse.
- Security Vulnerabilities
  - Added complexity
  - Unexpected Behavior
  - Spoofing
  - Command Injection

- Legal and Ethical Issues
  - Liability
  - Ethical dilemmas in decision-making
  - Deception
- Creation & Maintenance
  - Proper training data
  - Proper data labeling
  - Model degradation (drifting)
  - API and version compatibility
- Higher Resource Requirements
  - Heat and power



# VSS Challenge: Data for Global Model Training



- Advanced Driver Assistance Systems (ADAS)
  - Is recognition correct
  - When does the system deactivate itself
  - Driver recognized state vs performance
- Autonomous Driving
  - Is the fused world view correct?
  - Actual route vs best route
  - Driver interventions
  - Safety violations
  - Precrash Data

- Predictive Maintenance
  - Data around unexpected failures
- Vehicle User Interface
  - User feedback
- Cybersecurity
  - False positives
  - False responses
- Energy Management
  - Deviation between prediction and actual use
  - Ineffectiveness of operations

Model Updates Change Signal Profile!



# **System Requirements**



- Robust Application Over-the-Air Update
  - Incremental (modular)
  - Selfaware in-vehicle software framework
  - Version tracing and compatibility
- Dynamic Data Acquisition
  - Plan Updatable during operation
  - Vehicle specific signal catalogues
  - Uniformly named signals (VSS)
- Unit Carrying Signals
  - All values have measurement units, e.g., Degrees Fahrenheit
  - Simplified interpretation by Al models





## Software-Defined Data Collection



#### **Evolution of Data Collection**

Static Aquisition



Rules w/ Fixed Operations



Dynamic Network & Nodes

- Predefined Signals
- Limited control

- Downloadable Rules
- Predefined Signals
- Predefined Operations
- Frequency Control
- Event Triggers

- Network of Nodes
- Dynamically Updatable
- Dynamically Defined Nodes
- Based on Application Framework
- Eases Merging Multiple Data Aquisition Plans
- VSS selfawareness



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## **Vehicle Data Collection Process**



#### Conversion

- Convert native data to vehicle independent signals
- Partially covered by VSS
- No filtering
  - Only CAN & AUTOSAR signals.

Signal Conversion

Manifest

#### **Preprocessing**

- Compose signals not present natively.
- Compress data
- Store data
- React to triggers
- Subsystem modeling
- Interact w/ Al Model

**Software Bundles** 

#### Selection

- Decide what signals to send when
- Uses both converted signals and preprocessed data
- Describable as a network

**Data Acquisition Plan** 

#### **Transmission**

- Connect to server
- Transmit requested data
- Handle all failure
   modes such as
   network disconnect
   and server failure

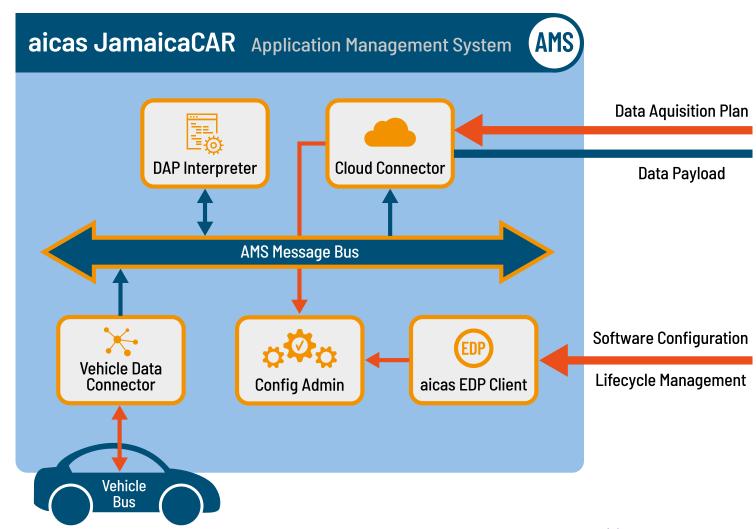
**Sparkplug** 



## Integrating Al into Data Collection



- Alls Al models must be field upgradable.
- 2. Signal catalogue must be dynamically updates
- 3. Data Acquistion Plan must be dynamically changeable
- 4. Fach vehicle must know what signal it can supply (selfawareness)
- There must be a well-defined process for updates of all three components.

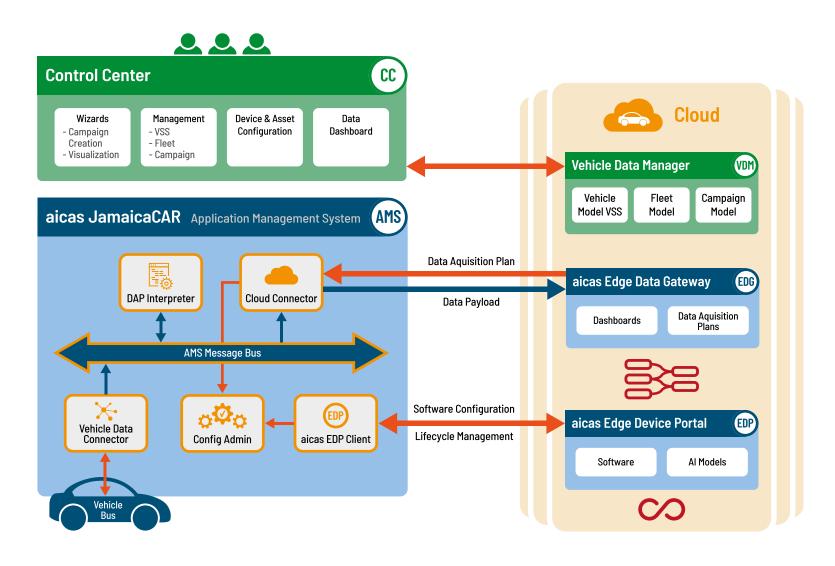




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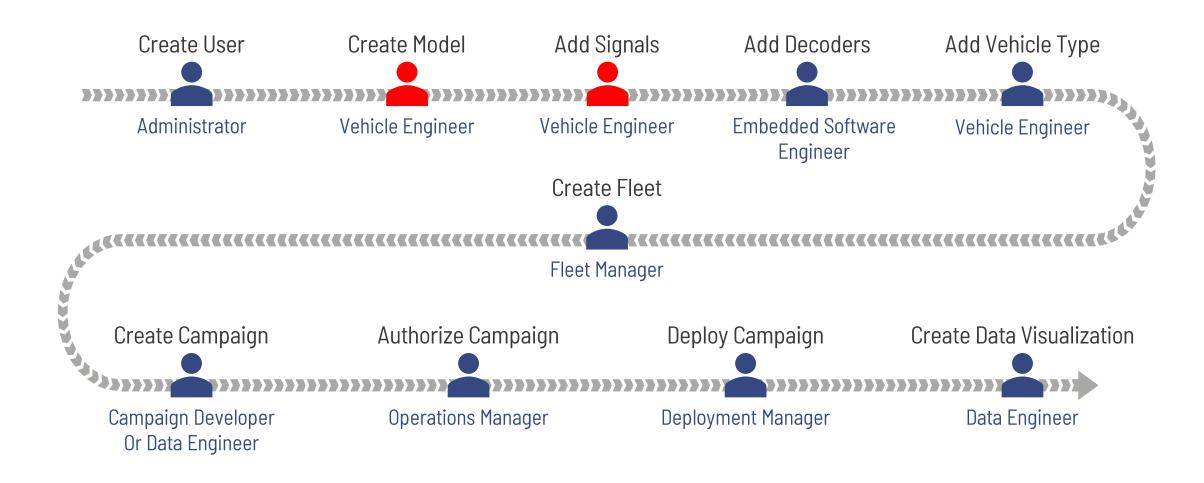
# **Vehicle Support Architecture**





### Role-Based Access







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# Who needs Data Collection? **Example Roles and Permissions**

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<b>Acquisition Element</b>	Create	Read	Use	Authorize	Update	Delete
Vehicle connector	ESW Eng	ESW Eng SW Eng	ESW Eng SW Eng	QΑ	ESW Eng	ESW Eng Ops Mgr
Enterprise VSS catalog	Vehicle Mgr	Vehicle Mgr SW Eng	Vehicle Mgr SW Eng	QΑ	Vehicle Mgr	Ops Mgr
DB Schema	IT Eng	IT Eng SW Eng	IT Eng SW Eng	QΑ	IT Eng	Ops Mgr
Vehicle Data	Vehicle Eng	Vehicle Eng Data User	Vehicle Eng Data User	Vehicle Mgr	Vehicle Eng	<b>Vehicle Mgr</b> Ops Mgr
Vehicle Definition (VSS)	Vehicle Eng	Vehicle Eng Data User	Vehicle Eng Data User	Vehicle Mgr	Vehicle Eng	Vehicle Mgr
Fleet	Fleet Mgr	Fleet Mgr Data User	Fleet Mgr	Deploy Mgr	Fleet Mgr	Fleet Mgr
Data Acquisition Plan	Data User	Data User	Data User	Deploy Mgr	Data User	Data User
Campaign	Data User	Data User	Data User	Ops Mgr	Data User	Data User
Visualization Template	UI Design	UI Design Data User	UI Design Data User	Data Mgr	UI Design	UI Design



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# Al Impact on Data Collection Process

- Data Collection and Model Generation Need Coordination
- Devops and data collection process must be interoperable
- Necessary to maximize business value creation and robustness



## **Tracing Software Providence**



UN

**Global Regulations** 

#### **Cyber Security and Software Updating**

- UNECE r155—vehicle cybersecurity and cybersecurity management systems
- UNECE r156—vehicle software updates and software update management systems

ISO

**Guidance and Best Practice** 

#### **Road Vehicles**

- ISO/SAE 21434:2021
   Cybersecurity engineering
- ISO 24089:2023 Software update engineering

US Government: EO 14028—SECURING THE SOFTWARE SUPPLY CHAIN



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# **Challenges of Regulatory Guidelines**

- Implicit assumption that software update is global: one number for everything
- Does not consider that the vehicle could track all installed software: selfawareness
- Does not address modular update
- If not handled correctly, this could be the death of the software defined vehicle

These issue can be handled through version naming conventions, but that is awkward



## Summary



- The use of Al increases vehicle functionality.
- It also increases 0EM risk.
- Robustness is paramount
  - Modular updatability
  - Well-defined unit carrying data (signals) and data catalogue (VSS)
  - Dynamic, synthetic signals
  - Seamless integration with and between Al models
  - Selfaware framework
- So is the Process
  - Role-based access w/ change review and testing process
  - Well documented change history



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Thank you for your attention! Please visit us this evening.

# Simplifying Edge-to-Cloud

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#### **Technical Presentation**



#### Integrating Al Models with Data Collection

2:05 PM - 2:25 PM Wednesday



Dr. James J. Hunt CEO & CTO - aicas GmbH

Machine Learning (ML) is a game changer for vehicle data collection. Most systems are still rather static, where a fixed set of signals are collected. There are 0EMS, that have systems, where data collection can be tailored using a data acquisition plan, either as collection rules or a data flow network. Even here, the challenge is to bring this flexibility to the customer. It is much easier to offer a selection of the signals already being collected than provide a system where the customer can select from the thousands of available signals and configure triggers and rates. Models could be used both to reduce the data that needs to be transmitted and help an 0EM data customer to provide a plan that provides only the data actually needed and combine different plans for deployment to a vehicle. This talk will discuss what is necessary to integrate ML with data collection.



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